







### **ECONOMIC & COMPACT** 3D GOES HIGH DEFINITION IN HIGH SPEED

HIGH SPEED 3D SCANNING FOR FASTER PRODUCTION LINES & THROUGHPUT ULTRA-HIGH RESOLUTION RESOLVE EXTREMELY FINE FEATURES SUPERIOR 3D IMAGE QUALITY BEST REPEATABILITY UNDER CHALLENGING CONDITIONS

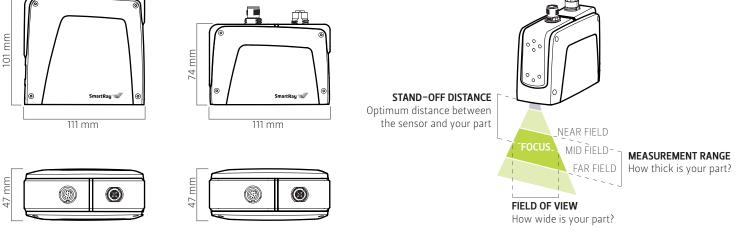
MODEL		ECCO 95.010	ECCO 95.040	ECCO 95.100		
Typical field of vie Measurement ran Stand–off distanc Typical vertical re Typical lateral res Weight Part number	e solution (Z) <sup>1</sup>	10.5   <b>11</b>   11.5 mm 4 mm 23.5 mm 0.37 – 0.45 μm 5.8 – 6.8 μm Approx. 650 g 3.002.152 (laser class 2M) 3.003.152 (laser class 3B)	34   <b>36</b>   38 mm 16 mm 60 mm 1.4 – 1.8 μm 18 – 20 μm Approx. 490 g 3.002.153 (laser class 2M) 3.003.153 (laser class 3B)	72   <b>98</b>   124 mm 100 mm 150 mm 5 - 12 μm 42 - 70 μm Approx. 490 g 3.002.150 (laser class 2M) 3.003.150 (laser class 3B)		
Maximum points /	-	1920 Approx. from 400 Hz up to 8				
Typical 3D point rate		Approx. from 0.7 up to 15 mi				
Interface		Gigabit Ethernet (1 Gbit/sec)				
Inputs		2 x Inputs, 5 – 24 VDC Quadrature Encoder (AB-Channel, RS-422 standard)				
Outputs		2 x Outputs, 24 VDC (max. 20 mA)				
Trigger		START Trigger support on Input 1–2 DATA Trigger support on Quadrature Encoder Input (Max. DATA trigger rate: 1 MHz) DATA Trigger support on Input 2 (Max. DATA trigger rate: 10 kHz)				
Input voltage   Power		24 VDC, ± 15% ripple   8.5 W				
Laser wavelength		450 nm				
Laser class	standard   optional	2M   3B				
Maximum ambier	nt light	10,000 lx				
EMC test		as per EN 61 000-6-2, EN 61	000-6-4			
Vibration / Shock	test	as per EN 60 068-2-6, -27,	-29, -64			
Electrical safetyas per EN 61 010-1-3Protection classIII, as per EN 61 040-3						
Enclosure rating		IP65				
Air humidity		Maximum 90%, non-condensing				
Temperature	operation   storage	0 - 40° C   -20 - 70° C				
Compatible acces	sories	Power-I/O-Encoder cable: 6 Ethernet cable: 6.303.0XX	.320.0XX			

1 2

Typical values can vary up to 5% due to optical tolerances Scan rate & point rate are dependent on the configured field of view, measurement range and exposure time. A ,scan' by definition considers maximum points/3D profile i.e. full FOV. The typical scan/point rate range has been estimated considering an exposure time of 1 µsec, min-max MR and full FOV. The typical scan rate can be further boosted by windowing the FOV



ECCO 95.040 | ECCO 95.100



SmartRay WWW CUTTING-EDGE 3D SENSORS FOR INSPECTION, GUIDANCE AND MEASUREMENT







# **3D GOES HD**

HIGH DEFINITION SENSORS OPEN UP RANGE OF NEW 3D APPLICATIONS

HIGHEST RESOLUTION IDENTIFY SMALLER DEFECTS INCREASED ACCURACY FOR PRECISE MEASUREMENT MORE 3D POINTS/SEC FOR FAST PRODUCTION LINES LARGER FIELD OF VIEW SCAN BIGGER OBJECTS

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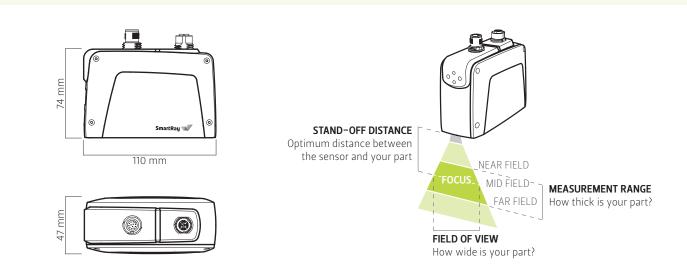
### ECC0 75.100 ECC0 75.200

Typical field of view <sup>1</sup> near   mid   far Measurement range <sup>1</sup> Stand-off distance Typical vertical resolution (Z) <sup>1</sup> Typical lateral resolution (Y) <sup>1</sup> Z-Linearity <sup>2,5</sup> Z-Repeatability <sup>4,5</sup> Weight Part number	34   <b>36</b>   38 mm 16 mm 60 mm 1.4 – 1.8 μm 18 – 20 μm 0.01% (0.1 μm/mm) 0.1 μm Approx. 480 g 3.002.121	72   <b>98</b>   124 mm 100 mm 150 mm 5 - 12 μm 42 - 70 μm 0.008% (0.08 μm/mm) 0.8 μm Approx. 480 g 3.002.120	125   <b>190</b>   250 mm 250 mm 325 mm 12 - 50 μm 66 - 138 μm 0.01% (0.1 μm/mm) 6 μm Approx. 480 g 3.002.124
Fait number	5.002.121	5.002.120	3.002.124
Maximum points / 3D profile Typical scan rate <sup>3</sup>	1920 Approx. from 150 Hz up to 4		
Typical 3D point rate <sup>3</sup> Interface	Approx. from 0.3 up to 7.6 r Gigabit Ethernet (1 Gbit/sec)	1	
Inputs	4 x Inputs, 5 – 24 VDC Quadrature Encoder (AB-Channel, RS–422 standard)		
Outputs	2 x Outputs, 24 VDC (max. 2		
Trigger		put 1–4 adrature Encoder Input (Max. ut 2, 3 (Max. DATA trigger rat	
Input voltage   Power	24 VDC, ± 15% ripple   7.5 W		/
Laser wavelength	660 nm		
Laser class standard   optional	2M   -		
Maximum ambient light	10,000 lx		
EMC test	as per EN 61 000-6-2, EN 6		
Vibration / Shock test	as per EN 60 068-2-6, -27	, -29, -64	
Electrical safety Protection class	as per EN 61 010-1-3 III, as per EN 61 040-3		
Enclosure rating	III, as per EN 01040-5		
Air humidity	Maximum 90%, non-conde	ensing	
<b>Temperature</b> operation   storage	0 - 40° C   -20 - 70° C		
Compatible accessories	Power-I/O-Encoder cable: Ethernet cable: 6.303.0XX	5.320.0XX	

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2 3

Typical values can vary up to 5% due to optical tolerances Z-Linearity calculated as variation of "bias" (reference value vs. measured value) over the measurement range. The %slope of a best-fit line from a plot of bias over measurement range represents Z-Linearity Scan rate & point rate are dependent on the configured field of view, measurement range and exposure time. The typical scan/point rate has been estimated with an exposure time of 1 µsec Experimentally assessed by scanning a measurement target moving over a conveyor belt 50 times. Measurement performed by averaging height values within the Z-Map image. No post-processing filters applied Measurements performed on a SmartRay standard artifact which is an aluminum flat surface painted matte white 4 5



SmartRay www cutting-edge 3D sensors for inspection, guidance and measurement





ECONOMIC & COMPACT FOR HIGHER SPEED APPLICATIONS

HIGH SCAN RATE FOR FAST PRODUCTION LINES EXCEPTIONAL VALUE BEST PRICE/PERFORMANCE SMALLEST LIGHTWEIGHT HOUSING EASY TO FIT ANYWHERE

Typical field of view <sup>1</sup> n	ear   <b>mid</b>   far			
Measurement range <sup>1</sup>				
Stand-off distance				
Typical vertical resolution (Z) <sup>1</sup>				
Typical lateral resolution	( <b>Y</b> ) 1			
Z–Linearity <sup>2,5</sup>				
Z–Repeatability 4,5				
Weight				
Part number				

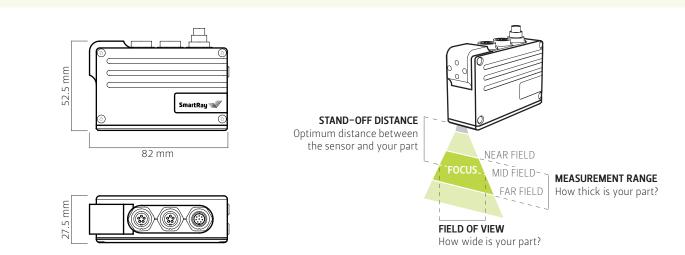
ECC0 55.020 ECC0 55.050 ECC0 55.100

Typical field of view <sup>1</sup> near   mid   far	22   <b>24</b>   26 mm	58   <b>69</b>   81 mm	88   <b>118</b>   148 mm		
Measurement range <sup>1</sup>	20 mm	60 mm	100 mm		
Stand-off distance	70 mm	150 mm	150 mm		
Typical vertical resolution (Z) <sup>1</sup>	3.25 – 4.75 µm	13.5 – 27 µm	19 – 53.5 µm		
Typical lateral resolution (Y) $^{\scriptscriptstyle 1}$	35 – 40 µm	85 – 115 µm	136 – 228 µm		
Z–Linearity <sup>2,5</sup>	0.01% (0.1 µm/mm)	0.01% (0.1µm/mm)	0.01% (0.1µm/mm)		
Z–Repeatability <sup>4,5</sup>	3.8 µm	1 µm	4.2 µm		
Weight	Approx. 180 g	Approx. 180 g	Approx. 180 g		
Part number	3.002.095	3.002.105	3.002.110		
Maximum points / 3D profile	640				
Typical scan rate <sup>3</sup>	Approx. from 400 Hz up to 6	kHz			
Typical 3D point rate <sup>3</sup>	Approx. from 0.3 up to 3.9 million points/sec				
Interface	Fast Ethernet (100 Mbit/sec)				
Inputs	4 x Inputs, 5 – 24 VDC				
	Quadrature Encoder (AB-Cha	,			
Outputs	2 x Outputs, 24 VDC (max. 20 mA)				
Trigger	START Trigger support on Inp	out 1 drature Encoder Input (Max.	DATA trigger rate: 100 kHz)		
		ut 2, 3 (Max. DATA trigger rate			
Input voltage   Power	24 VDC, ± 15% ripple   4.5 W				
Laser wavelength	660 nm				
Laser class standard   optional	2M   -				
Maximum ambient light	10,000 lx				
EMC test	as per EN 61 000-6-2, EN 61 000-6-4				
Vibration / Shock test	as per EN 60 068-2-6, -27, -29, -64				
Electrical safety	as per EN 61 010-1-3				
Protection class	III, as per EN 61 040-3				
Enclosure rating	IP65				
Air humidity	Maximum 90%, non-condensing				
Temperature operation   storage	0 – 40° C   –20 – 70° C				
Compatible accessories	Power-I/O cable: 6.310.0XX Ethernet cable: 6.302.0XX Encoder cable: 6.307.0XX				

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2 3

Typical values can vary up to 5% due to optical tolerances Z-Linearity calculated as variation of "bias" (reference value vs. measured value) over the measurement range. The %slope of a best-fit line from a plot of bias over measurement range represents Z-Linearity Scan rate & point rate are dependent on the configured field of view, measurement range and exposure time. The typical scan/point rate has been estimated with an exposure time of 3 µsec Experimentally assessed by scanning a measurement target moving over a conveyor belt 50 times. Measurement performed by averaging height values within the Z-Map image. No post-processing filters applied 4 5 Measurements performed on a SmartRay standard artifact which is an aluminum flat surface painted matte white



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**ECONOMIC & COMPACT** FOR STRAIGHTFORWARD APPLICATIONS

**STANDARD SCAN RATE** FOR STRAIGHTFORWARD APPLICATIONS **EXCEPTIONAL VALUE** BEST PRICE/PERFORMANCE **SMALLEST LIGHTWEIGHT HOUSING** EASY TO FIT ANYWHERE

Stand-off distance

Z-Linearity 2,5

Part number

Weight

Interface

Inputs

Outputs

Trigger

Z-Repeatability 4,5

**Typical scan rate** <sup>3</sup>

Laser wavelength

**Electrical safety** 

**Protection class** 

**Enclosure rating** 

Air humidity

Temperature

Laser class

EMC test

EC	CO	25	050
EU	U	<b>JJ</b> .	050

# ECCO 35.100

41 | **49** | 57 mm Typical field of view 1 near | mid | far 61 | 82 | 103 mm Measurement range 1 60 mm 100 mm 150 mm 150 mm Typical vertical resolution (Z) <sup>1</sup> 8.5 – 16.5 µm 11.5 – 32.5 µm Typical lateral resolution (Y) <sup>1</sup> 82 – 135 µm 57 - 80 µm 0.01% (0.1µm/mm) 0.02% (0.2 µm/mm) 1.8 µm 3.8 µm Approx. 180 g Approx. 180 g 3.002.005 3.002.010 Maximum points / 3D profile 752 Approx. from 100 Hz up to 500 Hz Typical 3D point rate <sup>3</sup> Approx. from 0.07 up to 0.3 million points/sec Fast Ethernet (100 Mbit/sec) 4 x Inputs, 5 - 24 VDC Quadrature Encoder (AB-Channel, RS-422 standard) 2 x Outputs, 24 VDC (max. 20 mA) START Trigger support on Input 1 DATA Trigger support on Quadrature Encoder Input (Max. DATA trigger rate: 100 kHz) DATA Trigger support on Input 2, 3 (Max. DATA trigger rate: 10 kHz) Input voltage | Power 24 VDC, ± 15% ripple | 4.5 W 660 nm standard | optional 2M | -Maximum ambient light 10,000 lx as per EN 61000-6-2, EN 61000-6-4 Vibration / Shock test as per EN 60 068-2-6, -27, -29, -64 as per EN 61 010-1-3 III, as per EN 61 040-3 IP65

Maximum 90%, non-condensing 0 - 40° C | -20 - 70° C operation | storage

**Compatible accessories** 

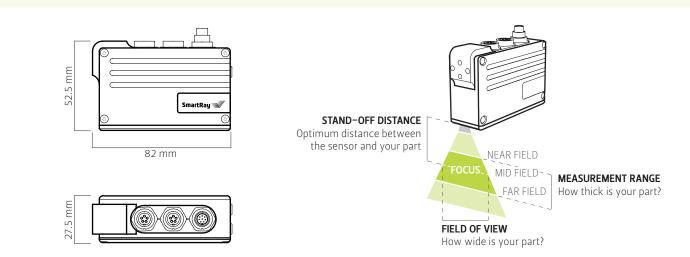
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Typical values can vary up to 5% due to optical tolerances Z-Linearity calculated as variation of "bias" (reference value vs. measured value) over the measurement range. The %slope of a best-fit line from a plot of bias over measurement range represents Z-Linearity 3

Power-I/O cable: 6.310.0XX

Ethernet cable: 6.302.0XX Encoder cable: 6.307.0XX

Experimentally assessed by scanning a measurement target moving over a conveyor belt 50 times. Measurement performed by averaging height values within the Z-Map image. No post-processing filters applied 5 Measurements performed on a SmartRay standard artifact which is an aluminum flat surface painted matte white



### Typical field of view 1 near | mid | far Measurement range 1 Stand-off distance Typical vertical resolution (Z)<sup>1</sup> Typical lateral resolution (Y) <sup>1</sup> Z–Linearity <sup>2,5</sup> Z-Repeatability 4,5 Weight Part number

Maximum points / 3D profile Typical scan rate <sup>3</sup> Typical 3D point rate <sup>3</sup> Interface Inputs

Outputs Trigger

Input voltage | Power Laser wavelength Laser class standard | optional Maximum ambient light **EMC test** Vibration / Shock test **Electrical safety Protection class Enclosure rating** Air humidity Temperature operation | storage **Compatible accessories** 

# SR5650@85



26.5 | **27** | 27.5 mm 4 mm 85 mm 2.1 - 2.2 25 - 26 µm 0.03% (0.3 µm/mm) 0.6 µm Approx. 2300 g 3.003.030

1777

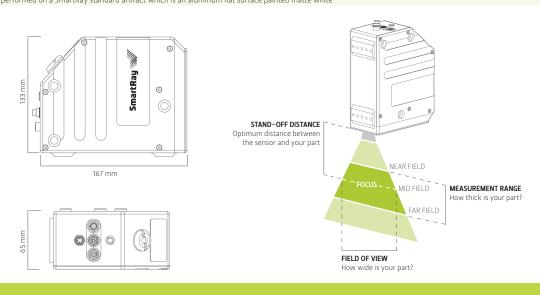


1272
Approx. from 4 kHz up to 25 kHz
Approx. from 5 up to 32 million points/sec
Gigabit Ethernet (1 Gbit/sec)
4 x Inputs, 5 – 24 VDC
Quadrature Encoder (AB-Channel, RS-422 standard)
2 x Outputs, 24 VDC (max. 20 mA)
START Trigger support on Input 1
DATA Trigger support on Quadrature Encoder Input (Max. DATA trigger rate: 100 kHz) DATA Trigger support on Input 2, 3 (Max. DATA trigger rate: 10 kHz)
24 VDC, ± 15% ripple   13 W
660 nm
3R   -
10,000 lx
as per EN 61 000-6-2, EN 61 000-6-4
as per EN 60 068-2-6, -27, -29, -64
as per EN 61 010-1-3
III, as per EN 61 040-3
IP65
Maximum 90%, non-condensing
0 – 40° C   –20 – 70° C
Power-I/O cable: 6.310.0XX Ethernet cable: 6.302.0XX Encoder cable: 6.307.0XX

1

2 3

Typical values can vary up to 10% due to optical tolerances Z-Linearity calculated as variation of "bias" (reference value vs. measured value) over the measurement range. The %slope of a best-fit line from a plot of bias over measurement range represents Z-Linearity Scan rate & point rate are dependent on the configured field of view, measurement range and exposure time. The typical scan/point rate has been estimated with an exposure time of 3 µsec Experimentally assesed by scanning a measurement target moving over a conveyor belt 50 times. Measurement performed by averaging height values within the Z-Map image. No post-processing filters applied Measurements performed on a SmartRay standard artifact which is an aluminum flat surface painted matte white 5



Typical field of view <sup>1</sup> near | mid | far Measurement range <sup>1</sup> Stand-off distance Typical vertical resolution (Z)<sup>1</sup> Typical lateral resolution (Y)<sup>1</sup> Z-Linearity 2,5 Z-Repeatability 4,5 Weight Part number (laser class 2M | 3B)

Maximum points / 3D profile Typical scan rate <sup>3</sup> Typical 3D point rate <sup>3</sup> Interface Inputs

### Outputs Trigger

Input voltage | Power Laser wavelength Laser class standard | optional Maximum ambient light EMC test Vibration / Shock test Electrical safety Protection class **Enclosure rating** Air humidity Temperature operation | storage Compatible accessories

### SR9628@160

118 | 130 | 142 mm 60 mm 160 mm 6.5 - 9 μm 92 - 110 µm 0.008% (4.8 µm/mm) 1.4 µm Approx. 1900 g 3.003.001 | 3.003.002 295 | 310 | 328 mm 140 mm 500 mm 46 - 56 µm 225 - 310µm 0.025% (35 µm/mm) 6 µm Approx. 1900 g 3.003.025 | 3.003.026



we live 3D

SmartRay

1272
Approx. from 2.5 kHz up to 25 kHz
Approx. from 3.2 up to 32 million points/sec
Gigabit Ethernet (1 Gbit/sec)
4 x Inputs, 5 - 24 VDC
Quadrature Encoder (AB-Channel, RS-422 standard)
2 x Outputs, 24 VDC (max. 20 mA)
START Trigger support on Input 1
DATA Trigger support on Quadrature Encoder Input (Max. DATA trigger rate: 100 kHz)
DATA Trigger support on Input 2, 3 (Max. DATA trigger rate: 10 kHz)
24 VDC, ± 15% ripple   13 W
660 nm
2M   3B
10,000 lx
as per EN 61 000-6-2, EN 61 000-6-4
as per EN 60 068-2-6, -27, -29, -64
as per EN 61 010-1-3
III, as per EN 61 040-3
IP65
Maximum 90%, non-condensing
0 - 40° C   -20 - 70° C
Power-I/O cable: 6.310.0XX
Ethernet cable: 6.302.0XX
Encoder cable: 6.307.0XX

1

Typical values can vary up to 5% due to optical tolerances Z-Linearity calculated as variation of "bias" (reference value vs. measured value) over the measurement range. The %slope of a best-fit line from a plot of bias over measurement range represents Z-Linearity 2 3

- Scan rate & point rate are dependent on the configured field of view, measurement range and exposure time. The typical scan/point rate has been estimated with an exposure time of 1 µsec Experimentally assessed by scanning a measurement target moving over a conveyor belt 50 times. Measurement performed by averaging height values within the Z-Map image. No post-processing filters applied Measurements performed on a SmartRay standard artifact which is an aluminum flat surface painted matte white 5
  - 167 mm STAND-OFF DISTANCE Optimum distance between the sensor and your part NEAR FIELD 175 mm MIDFIELD MEASUREMENTRANGE low thick is your part? FAR FIFLD 0 Ø 0 FIELD OF VIEW

How wide is your part?

SR9628@500